Package: rjd3nowcasting (via r-universe)

September 17, 2024

Type Package

Title Nowcasting with 'JDemetra+ 3.0'

Version 2.0.3.9000

Description Interface around 'JDemetra+ 3.x'
(<<https://github.com/jdemetra/jdplus-nowcasting>>), TSACE
project. It defines and estimates Dynamic Factor Models with
the purpose of Nowcasting. News analysis is included in this
second version.

Depends R (>= 4.1.0)

Imports rJava (>= 1.0-6), rjd3toolkit (>= 3.2.2)

Remotes github::rjdverse/rjd3toolkit

SystemRequirements Java (>= 17)

License EUPL

URL <https://github.com/rjdverse/rjd3nowcasting>,
<https://rjdverse.github.io/rjd3nowcasting/>

BugReports <https://github.com/rjdverse/rjd3nowcasting/issues>

Encoding UTF-8

Collate 'data.R' 'estimation.R' 'news.R' 'results.R' 'zzz.R'

RoxygenNote 7.3.1

Suggests knitr, rmarkdown

VignetteBuilder knitr

LazyData true

Repository https://tanguybarthelemy.r-universe.dev

RemoteUrl https://github.com/rjdverse/rjd3nowcasting

RemoteRef HEAD

RemoteSha c436ed80f913a3504bb9dd74646f903e7d335892

Contents

---

create_model   *Create Dynamic Factor Model*

Description

Create Dynamic Factor Model

Usage

```
create_model(
  nfactors,
  nlags,
  factors_type,
  factors_loading,
  var_init = c("Unconditional", "Zero"),
  var_coefficients = NULL,
  var_errors_variance = NULL,
  measurement_coefficients = NULL,
  measurement_errors_variance = NULL
)
```

Arguments

nfactors	Integer. Number of factors.
nlags	Integer. Number of lags in VAR equations.
factors_type	Character vector. Respecting the order of the series in the input data, you must refer here the link between the (transformed) series and the factors. Three options are possible:

- "M": Variables expressed in terms of monthly growth rates can be linked to a factor representing the underlying monthly growth rate of the economy if "M" is selected
- "Q": Monthly or quarterly variables that are correlated with the the underlying quarterly growth rate of the economy can be linked to a weighted average of the factors representing the underlying monthly growth rate of the economy. Such a weighted average is meant to represent quarterly growth rates, and it is implemented by selecting "Q"
- "YoY": The variables can also be linked to the cumulative sum of the last 12 monthly factors. If the model is designed in such a way that the monthly factors represent monthly growth rates, the resulting cumulative sum boils down to the year-on-year growth rate. Thus, variables expressed in terms of year-on-year growth rates or surveys that are correlated with the year-on-year growth rates of the reference series should be linked to the factors using "YoY".

factors_loading

Boolean matrix. It represents the factor loading structure. The dimension of the matrix should be 'number of series' x 'number of factors'. For each row representing each series, the user must mention whether the corresponding factor loads on this series.

var_init   Character. The first unobserved factors values in the sample is assumed to be either equal to zero or consistent with a normal distribution with mean zero and a variance corresponding to the unconditional variance of the VAR. The latter is the default.

var_coefficients

Matrix. The default is NULL meaning that the VAR coefficients will be estimated from scratch. Alternatively, a matrix of pre-defined values can be passed in. Those would come typically from a previous model estimate and will serve as a starting point for the estimation step. The format of the matrix should be the same as the one produced by default by the create_model() function while keeping the 'var_coefficients' argument to its default value NULL.

var_errors_variance

Matrix. The default is NULL meaning that the VAR errors variance will be estimated from scratch. Alternatively, a matrix of pre-defined values can be passed in. Those would come typically from a previous model estimate and will serve as a starting point for the estimation step. The format of the matrix should be the same as the one produced by default by the create_model() function while keeping the 'var_errors_variance' argument to its default value NULL.

measurement_coefficients

Matrix. The default is NULL meaning that the measurement coefficients will be estimated from scratch. Alternatively, a matrix of pre-defined values can be passed in. Those would come typically from a previous model estimate and will serve as a starting point for the estimation step. The format of the matrix should be the same as the one produced by default by the create_model() function while keeping the 'measurement_coefficients' argument to its default value NULL.

measurement_errors_variance

Numeric vector. The default is NULL meaning that the measurement errors variance will be estimated from scratch. Alternatively, a vector of pre-defined values

can be passed in. Those would come typically from a previous model estimate and will serve as a starting point for the estimation step. The format of the vector should be the same as the one produced by default by the create_model() function while keeping the 'measurement_errors_variance' argument to its default value NULL.

Value

an object of class 'JD3_DfmModel'

Examples

```
# From scratch
dfm1 <- create_model(nfactors=2,
                     nlags=2,
                     factors_type = c("M", "M", "YoY", "M", "Q"),
                     factors_loading = matrix(data=TRUE, 5, 2),
                     var_init = "Unconditional")

# From a previous estimate
set.seed(100)
data<-ts(matrix(rnorm(500), 100, 5), frequency = 12, start = c(2010,1))
data[100,1]<-data[99:100,2]<-data[(1:100)[-seq(3,100,3)],5]<-NA
est1<-estimate_em(dfm1, data)

dfm2 <- create_model(nfactors=2,
                     nlags=2,
                     factors_type = c("M", "M", "YoY", "M", "Q"),
                     factors_loading = matrix(data=TRUE, 5, 2),
                     var_init = "Unconditional",
                     var_coefficients = est1$dfm$var_coefficients,
                     var_errors_variance = est1$dfm$var_errors_variance,
                     measurement_coefficients = est1$dfm$measurement_coefficients,
                     measurement_errors_variance = est1$dfm$measurement_errors_variance)
#est2<-estimate_em(dfm2, data)
```

---

estimate_em   *Estimate DFM with Expectations-Maximization algorithm*

Description

Estimate DFM with Expectations-Maximization algorithm

Usage

```
estimate_em(
  dfm,
  data,
```

```
      standardized = FALSE,
      input_standardization = NULL,
      pca_init = TRUE,
      max_iter = 100,
      eps = 1e-09,
      re_estimate = TRUE
)
```

Arguments

dfm	an object of class 'JD3_DfmModel'. Typically generated by the create_model() function.
data	an mts object.
standardized	Boolean. Indicate whether the input series were already standardized or not. Default is FALSE, meaning that a standardization of the series will be preliminary applied as part of the process.
input_standardization	
	Matrix. Mean and standard deviation of the variables to consider for the pre-processing step of standardization. Default is NULL, meaning that they will be re-calculated based on the data. Typically, it can be filled with the output of the function 'get_results()$preprocessing$sample_mean_stdev' applied on a previous estimate of the model. If provided manually, it must be a two columns matrix with the mean in the first column and the standard deviation in the second column. In the rows, the order of the variables should also be respected (similar to the data). Note that this argument must be filled if the re_estimate argument is set to FALSE. On the other hand, it is ignored if the standardized argument is set to TRUE.
pca_init	Boolean. Indicate whether a principal components analysis is performed before-hand and used as initial condition for the EM algorithm.
max_iter	Integer. Maximum number of iterations.
eps	Numeric. EM algorithm is run until the percentage likelihood does not increase by more than the eps value (1e-9 is the default) or until the maximum number of iterations is hit.
re_estimate	Boolean. Indicate whether the model will be re-estimated or not. Default is TRUE. Could be set to FALSE if, for some reasons during the production process, we wanted to freeze to model for some periods of time. It is not recommended to freeze the model for a long period.

Value

an object of class 'JD3_DfmEstimates'

Examples

```
set.seed(100)
data<-ts(matrix(rnorm(500), 100, 5), frequency = 12, start = c(2010,1))
data[100,1]<-data[99:100,2]<-data[(1:100)[-seq(3,100,3)],5]<-NA
```

```
dfm <- create_model(nfactors=2,
                    nlags=2,
                    factors_type = c("M", "M", "YoY", "M", "Q"),
                    factors_loading = matrix(data=TRUE, 5, 2),
                    var_init = "Unconditional")
est_em<-estimate_em(dfm, data)

#est_em<-estimate_em(dfm, data, re_estimate=FALSE) # model not re-estimated
```

---

estimate_ml   *Estimate DFM with Maximum Likelihood*

Description

Estimate DFM with Maximum Likelihood

Usage

```
estimate_ml(
  dfm,
  data,
  standardized = FALSE,
  input_standardization = NULL,
  pca_init = TRUE,
  em_init = TRUE,
  em_max_iter = 100,
  em_eps = 1e-09,
  max_iter = 1000,
  max_block_iter = 5,
  simpl_model_iter = 15,
  independent_var_shocks = FALSE,
  mixedEstimation = TRUE,
  eps = 1e-09,
  re_estimate = TRUE
)
```

Arguments

dfm	an object of class 'JD3_DfmModel'. Typically generated by the create_model() function.
data	an mts object.
standardized	Boolean. Indicate whether the input series were already standardized or not. Default is FALSE, meaning that a standardization of the series will be preliminary applied as part of the process.

input_standardization

> Matrix. Mean and standard deviation of the variables to consider for the pre-processing step of standardization. Default is NULL, meaning that they will be re-calculated based on the data. Typically, it can be filled with the output of the function 'get_results()$preprocessing$sample_mean_stdev' applied on a previous estimate of the model. If provided manually, it must be a two columns matrix with the mean in the first column and the standard deviation in the second column. In the rows, the order of the variables should also be respected (similar to the data). Note that this argument must be filled if the re_estimate argument is set to FALSE. On the other hand, it is ignored if the standardized argument is set to TRUE.

pca_init

> Boolean. Indicate whether a principal components analysis is performed before-hand and used as initial condition for either the EM algorithm (if em_init=TRUE) or directly for the ML estimation.

em_init

> Boolean. Indicate whether the EM algorithm is performed beforehand and used as initial condition for the ML estimation.

em_max_iter

> Integer. Maximum number of iterations of the EM algorithm. Ignored if em_init = FALSE.

em_eps

> Numeric. EM algorithm is run until the percentage likelihood does not increase by more than the eps value (1e-9 is the default) or until the maximum number of iterations is hit. Ignored if em_init = FALSE.

max_iter

> Integer. Maximum number of iterations for the ML estimation.

max_block_iter

> Integer. Maximum number of iterations in optimization by block. The model parameters are divided in two blocks: one related to the measurement equations and one to the VAR equations. While the EM algorithm requires one iteration per block, the numerical optimization allows us to set the number of iterations desired per block.

simpl_model_iter

> Integer. Number of simplified model iterations allowed.

independent_var_shocks

> Boolean. Whether we assume that shocks in the VAR block are independent.

mixedEstimation

> Boolean. The mixed estimation option alternates between the iterations for the VAR block alone and simultaneous iterations for the two blocks.

eps

> Numeric. ML estimation is run until the percentage likelihood does not increase by more than the eps value (1e-9 is the default) or until the maximum number of iterations is hit.

re_estimate

> Boolean. Indicate whether the model will be re-estimated or not. Default is TRUE. Could be set to FALSE if, for some reasons during the production process, we wanted to freeze to model for some periods of time. It is not recommended to freeze the model for a long period.

Value

an object of class 'JD3_DfmEstimates'

Examples

```
set.seed(100)
data<-ts(matrix(rnorm(500), 100, 5), frequency = 12, start = c(2010,1))
data[100,1]<-data[99:100,2]<-data[(1:100)[-seq(3,100,3)],5]<-NA
dfm <- create_model(nfactors=2,
                    nlags=2,
                    factors_type = c("M", "M", "YoY", "M", "Q"),
                    factors_loading = matrix(data=TRUE, 5, 2),
                    var_init = "Unconditional")
est_ml<-estimate_ml(dfm, data)

#est_ml<-estimate_ml(dfm, data, re_estimate=FALSE) # model not re-estimated
```

---

estimate_pca   *Estimate DFM with Principal components Analysis*

Description

Estimate DFM with Principal components Analysis

Usage

```
estimate_pca(
  dfm,
  data,
  standardized = FALSE,
  input_standardization = NULL,
  re_estimate = TRUE
)
```

Arguments

dfm   an object of class 'JD3_DfmModel'. Typically generated by the create_model()
                      function.

data   an mts object.

standardized   Boolean. Indicate whether the input series were already standardized or not. De-
                      fault is FALSE, meaning that a standardization of the series will be preliminary
                      applied as part of the process.

input_standardization

                      Matrix. Mean and standard deviation of the variables to consider for the pre-
                      processing step of standardization. Default is NULL, meaning that they will
                      be re-calculated based on the data. Typically, it can be filled with the output
                      of the function 'get_results()$preprocessing$sample_mean_stdev' applied on a
                      previous estimate of the model. If provided manually, it must be a two columns
                      matrix with the mean in the first column and the standard deviation in the second
                      column. In the rows, the order of the variables should also be respected (similar

to the data). Note that this argument must be filled if the re_estimate argument is set to FALSE. On the other hand, it is ignored if the standardized argument is set to TRUE.

re_estimate   Boolean. Indicate whether the model will be re-estimated or not. Default is TRUE. Could be set to FALSE if, for some reasons during the production process, we wanted to freeze to model for some periods of time. It is not recommended to freeze the model for a long period.

Value

an object of class 'JD3_DfmEstimates'

Examples

```
set.seed(100)
data<-ts(matrix(rnorm(500), 100, 5), frequency = 12, start = c(2010,1))
data[100,1]<-data[99:100,2]<-data[(1:100)[-seq(3,100,3)],5]<-NA
dfm <- create_model(nfactors=2,
                    nlags=2,
                    factors_type = c("M", "M", "YoY", "M", "Q"),
                    factors_loading = matrix(data=TRUE, 5, 2),
                    var_init = "Unconditional")
est_pca<-estimate_pca(dfm, data)

#est_pca<-estimate_pca(dfm, data, re_estimate=FALSE) # model not re-estimated
```

---

get_forecasts   *Get DFM forecasts*

Description

Get DFM forecasts

Usage

```
get_forecasts(dfm_estimates, n_fcst = 3)
```

Arguments

dfm_estimates   an object of class 'JD3_DfmEstimates'

n_fcst   Integer. Number of forecast periods required.

Value

an object of class 'JD3_DfmForecasts'

Examples

```
set.seed(100)
data<-ts(matrix(rnorm(500), 100, 5), frequency = 12, start = c(2010,1))
data[100,1]<-data[99:100,2]<-data[(1:100)[-seq(3,100,3)],5]<-NA
dfm <- create_model(nfactors=2,
                     nlags=2,
                     factors_type = c("M", "M", "YoY", "M", "Q"),
                     factors_loading = matrix(data=TRUE, 5, 2),
                     var_init = "Unconditional")
est_em<-estimate_em(dfm, data)
fcst<-get_forecasts(est_em, n_fcst = 2)
```

---

get_news   *DFM News analysis*

Description

DFM News analysis

Usage

```
get_news(dfm_estimates, new_data, target_series = NULL, n_fcst = 3)
```

Arguments

dfm_estimates	an object of class 'JD3_DfmEstimates'. Typically generated by the functions estimate_pca(), estimate_em() or estimate_ml().
new_data	an mts object containing the updated dataset.
target_series	the name of the series of interest. By default, the first series is considered.
n_fcst	the number of forecasting periods to consider. Default is 3.

Value

An object of class 'JD3_DfmNews'

References

Banbura and Modugno (2010) - Maximum likelihood estimation of factor models on data sets with arbitrary pattern of missing data

Examples

```
set.seed(100)
data_t1<-ts(matrix(rnorm(500), 100, 5), frequency = 12, start = c(2010,1))
data_t1[100,1]<-data_t1[99:100,2]<-data_t1[(1:100)[-seq(3,100,3)],5]<-NA
data_t2<-ts(rbind(data_t1, rep(NA,5)), frequency = 12, start = c(2010,1))
data_t2[100,1]<-data_t2[99,2]<-data_t2[101,3]<-data_t2[101,4]<-1

dfm_model <- create_model(nfactors=2,
                          nlags=2,
                          factors_type = c("M", "M", "YoY", "M", "Q"),
                          factors_loading = matrix(TRUE, 5, 2),
                          var_init = "Unconditional")

est_em<-estimate_em(dfm_model, data_t1)
# or to use any previous frozen model:
# est_em_frozen<-estimate_em(dfm_model, data_t1, re_estimate = FALSE)

news<-get_news(est_em, data_t2, target_series = "Series 2", n_fcst = 2)
```

---

get_results *Get DFM results*

Description

Get DFM results

Usage

```
get_results(dfm_estimates)
```

Arguments

dfm_estimates   an object of class 'JD3_DfmEstimates'

Value

an object of class 'JD3_DfmResults'

Examples

```
set.seed(100)
data<-ts(matrix(rnorm(500), 100, 5), frequency = 12, start = c(2010,1))
data[100,1]<-data[99:100,2]<-data[(1:100)[-seq(3,100,3)],5]<-NA
dfm <- create_model(nfactors=2,
                    nlags=2,
                    factors_type = c("M", "M", "YoY", "M", "Q"),
                    factors_loading = matrix(data=TRUE, 5, 2),
                    var_init = "Unconditional")
```

```
est_em<-estimate_em(dfm, data)
rslt_em<-get_results(est_em)
```

---

macroIndicators   *Datasets including some French macro-economic variables*

Description

The datasets 'data0' and 'data1' acts as successive releases of macro-economic time series. They contain data on monthly industrial production index (PVI), turnover (TURN), quarterly GDP, as well as business survey data (BS) and other survey data (PMI) for both France and the Eurozone. Those datasets are used to illustrate how one of these variable can be nowcasted using the others using a Dynamic Factor model.

Usage

```
data0

data1
```

Format

An object of class data.frame with 150 rows and 11 columns.

An object of class data.frame with 150 rows and 11 columns.

---

plot.JD3_DfmForecasts   *Plot function for objects of class 'JD3_DfmForecasts'*

Description

Plot function for objects of class 'JD3_DfmForecasts'

Usage

```
## S3 method for class 'JD3_DfmForecasts'
plot(x, series_name = NULL, ...)
```

Arguments

x	an object of class 'JD3_DfmForecasts'
series_name	Character. Name of the series to plot. By default, the first series will be plotted.
...	further arguments passed to ts.plot().

---

plot.JD3_DfmNews *Plot function for objects of class 'JD3_DfmNews'*

Description

Plot function for objects of class 'JD3_DfmNews'

Usage

```
## S3 method for class 'JD3_DfmNews'
plot(x, ...)
```

Arguments

x   an object of class 'JD3_DfmNews'

...   further arguments passed to barplot().

---

print.JD3_DfmEstimates

  Print function for objects of class 'JD3_DfmEstimates'

Description

Print function for objects of class 'JD3_DfmEstimates'

Usage

```
## S3 method for class 'JD3_DfmEstimates'
print(x, ...)
```

Arguments

x   an object of class 'JD3_DfmEstimates'

...   further arguments passed to the print() function.

---

print.JD3_DfmForecasts

Print function for objects of class 'JD3_DfmForecasts'

Description

Print function for objects of class 'JD3_DfmForecasts'

Usage

```
## S3 method for class 'JD3_DfmForecasts'
print(x, ...)
```

Arguments

x   an object of class 'JD3_DfmForecasts'

...   further arguments passed to the print() function.

---

print.JD3_DfmNews   *Print function for objects of class 'JD3_DfmNews'*

Description

Print function for objects of class 'JD3_DfmNews'

Usage

```
## S3 method for class 'JD3_DfmNews'
print(x, ...)
```

Arguments

x   an object of class 'JD3_DfmNews'

...   further arguments passed to the print() function.

---

print.JD3_DfmResults   *Print function for objects of class 'JD3_DfmResults'*

Description

Print function for objects of class 'JD3_DfmResults'

Usage

```
## S3 method for class 'JD3_DfmResults'
print(x, ...)
```

Arguments

x	an object of class 'JD3_DfmResults'
...	further arguments passed to the print() function.

---

summary.JD3_DfmNews   *Summary function for objects of class 'JD3_DfmNews'*

Description

Summary function for objects of class 'JD3_DfmNews'

Usage

```
## S3 method for class 'JD3_DfmNews'
summary(object, ...)
```

Arguments

object	an object of class 'JD3_DfmNews'
...	further arguments passed to the print() function.

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